



Chapter 14 excerpts

Graphs (breadth-first-search) CS102 Sections 51 and 52 Marc Smith and Jim Ten Eyck Spring 2008

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14-1

Terminology

- $G = \{V, E\}$
- A graph G consists of two sets
 - A set V of vertices, or nodes
 - A set E of edges
- A subgraph
 - Consists of a subset of a graph's vertices and a subset of its edges
- Adjacent vertices
 - Two vertices that are joined by an edge

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14-2

Terminology

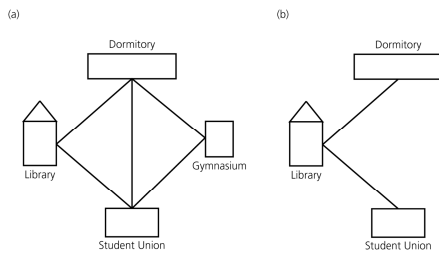


Figure 14-2
a) A campus map as a graph; b) a subgraph

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14-3

Terminology

- A path between two vertices
 - A sequence of edges that begins at one vertex and ends at another vertex
 - May pass through the same vertex more than once
- A simple path
 - A path that passes through a vertex only once
- A cycle
 - A path that begins and ends at the same vertex
- A simple cycle
 - A cycle that does not pass through a vertex more than once

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14-4

Terminology

- A connected graph
 - A graph that has a path between each pair of distinct vertices
- A disconnected graph
 - A graph that has at least one pair of vertices without a path between them
- A complete graph
 - A graph that has an edge between each pair of distinct vertices

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14-5

Terminology

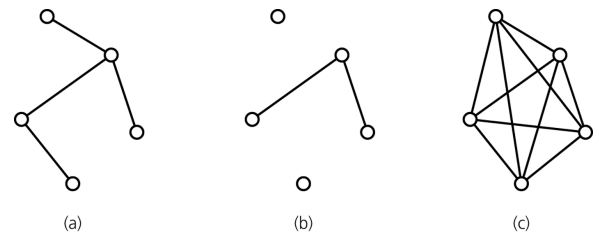


Figure 14-3
Graphs that are a) connected; b) disconnected; and c) complete

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14-6

Graphs As ADTs

- Graphs can be used as abstract data types
- Two options for defining graphs
 - Vertices contain values
 - Vertices do not contain values
- Operations of the ADT graph
 - Create an empty graph
 - Determine whether a graph is empty
 - Determine the number of vertices in a graph
 - Determine the number of edges in a graph

Graphs As ADTs

- Operations of the ADT graph (Continued)
 - Determine whether an edge exists between two given vertices; for weighted graphs, return weight value
 - Insert a vertex in a graph whose vertices have distinct search keys that differ from the new vertex's search key
 - Insert an edge between two given vertices in a graph
 - Delete a particular vertex from a graph and any edges between the vertex and other vertices
 - Delete the edge between two given vertices in a graph
 - Retrieve from a graph the vertex that contains a given search key

Implementing Graphs

- Most common implementations of a graph
 - Adjacency matrix
 - Adjacency list
- Adjacency matrix
 - Adjacency matrix for a graph with n vertices numbered $0, 1, \dots, n-1$
 - An n by n array matrix such that $\text{matrix}[i][j]$ is
 - 1 (or true) if there is an edge from vertex i to vertex j
 - 0 (or false) if there is no edge from vertex i to vertex j

Implementing Graphs

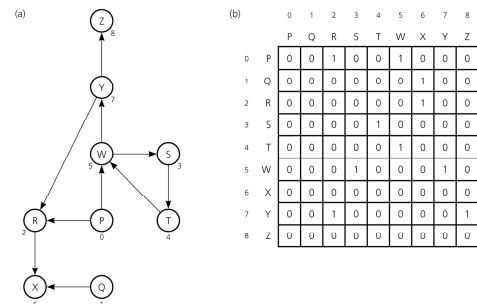


Figure 14-6

a) A directed graph and b) its adjacency matrix

Implementing Graphs

- Adjacency list
 - An adjacency list for a graph with n vertices numbered $0, 1, \dots, n-1$
 - Consists of n linked lists
 - The i^{th} linked list has a node for vertex j if and only if the graph contains an edge from vertex i to vertex j
 - This node can contain either
 - » Vertex j 's value, if any
 - » An indication of vertex j 's identity

Implementing Graphs

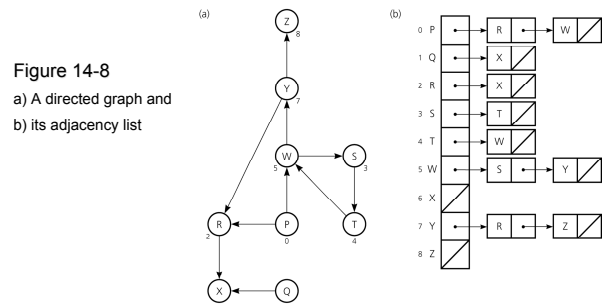


Figure 14-8

a) A directed graph and b) its adjacency list

Graph Traversals

- A graph-traversal algorithm
 - Visits all the vertices that it can reach
 - Visits all vertices of the graph if and only if the graph is connected
 - A connected component
 - The subset of vertices visited during a traversal that begins at a given vertex
 - Can loop indefinitely if a graph contains a loop
 - To prevent this, the algorithm must
 - Mark each vertex during a visit, and
 - Never visit a vertex more than once

Graph Traversals

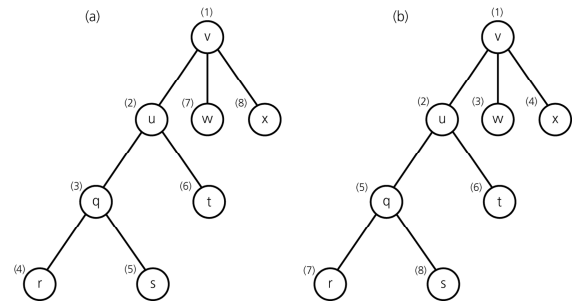


Figure 14-10

Visitation order for a) a depth-first search; b) a breadth-first search

Depth-First Search

- Depth-first search (DFS) traversal
 - Proceeds along a path from v as deeply into the graph as possible before backing up
 - Does not completely specify the order in which it should visit the vertices adjacent to v
 - A last visited, first explored strategy

Breadth-First Search

- Breadth-first search (BFS) traversal
 - Visits every vertex adjacent to a vertex v that it can before visiting any other vertex
 - A first visited, first explored strategy
 - An iterative form uses a queue
 - A recursive form is possible, but not simple